

Two-Photon Dual-Comb LiDAR for Non-Cooperative Targets

Alexander J M Nelmes

Dr Hollie Wright, Prof. Derryck T Reid

Institute of Photonics and Quantum Sciences

Heriot-Watt University

www.ultrafast.hw.ac.uk

Outline

1. Introduction
 - a. Overview
 - b. Industrial Applications
2. Two-photon dual-comb LiDAR
 - a. Optical Concepts
 - b. Electrical operations
 - c. Non-cooperative target measurements
3. Conclusion

Introduction – Overview:

Motivations

- Absolute distance measurements
- Ranging at μm -level precision and at kHz-level update rate
- Using eye-safe lasers at a wavelength of 1550 nm

Two-photon dual-comb LiDAR

HOLLIE WRIGHT,¹ JINGHUA SUN,^{1,2} DAVID MCKENDRICK,³ NICK WESTON,³ AND DERRYCK T. REID^{1,*} 

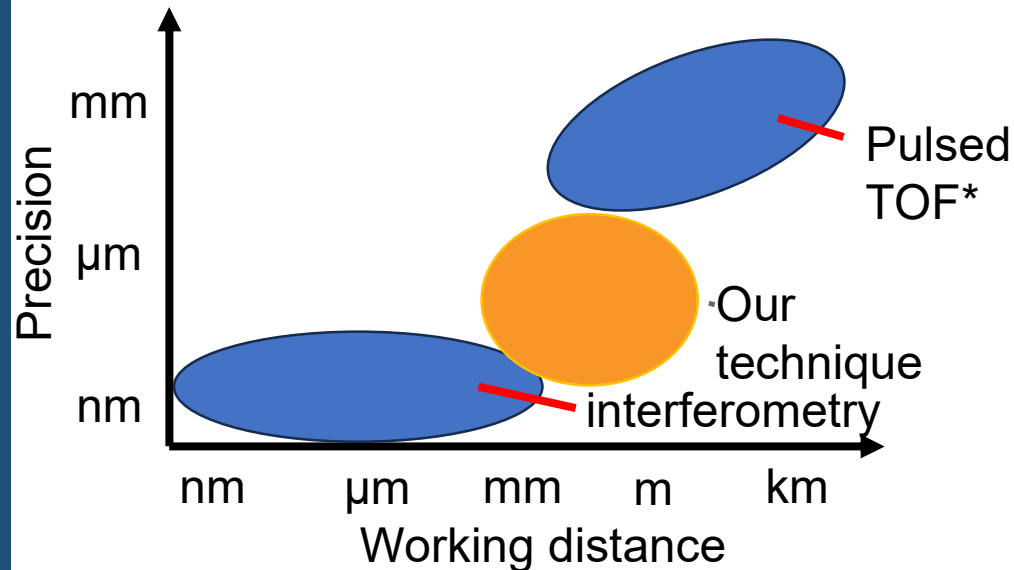
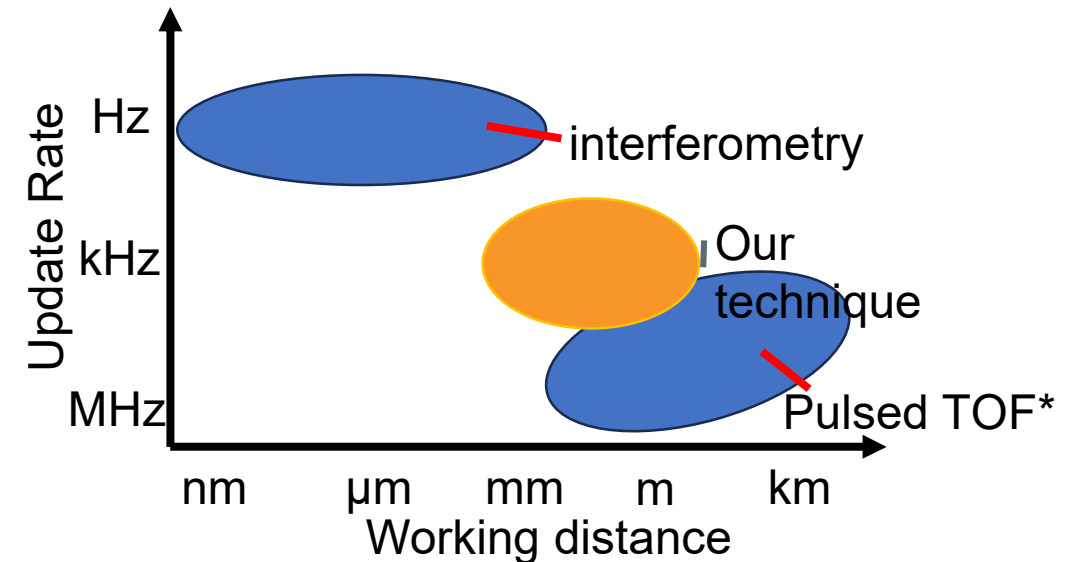
¹Scottish Universities Physics Engineering and Physical S
²School of Electronic Engin
Guangdong 523808, China
³Renishaw plc, Edinburgh,
*D.T.Reid@hw.ac.uk

Multi-target two-photon dual-comb LiDAR

HOLLIE WRIGHT,^{1,*}  ALEXANDER J. M. NELMES,¹ NICK J. WESTON,² AND DERRYCK T. REID¹ 

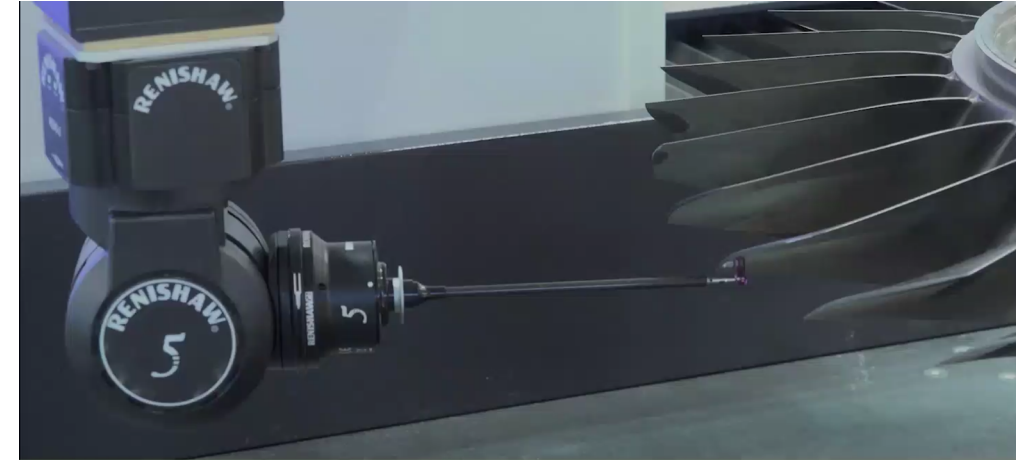
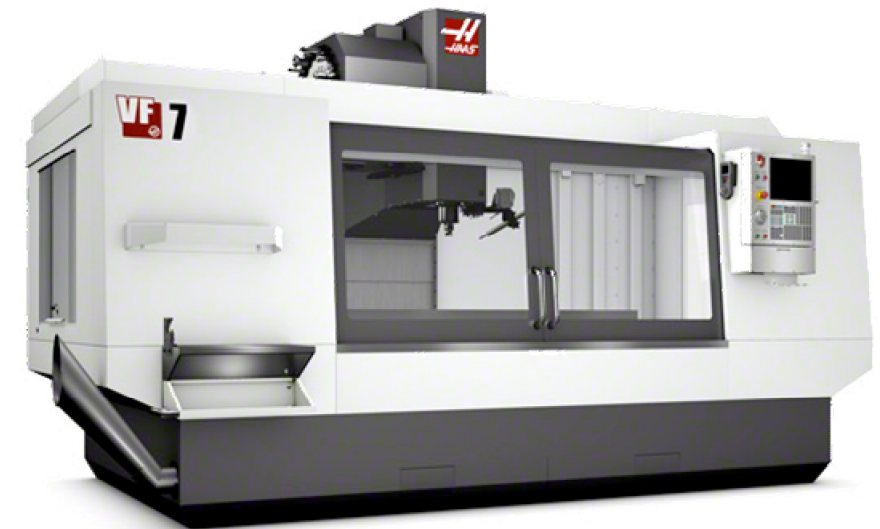
¹Scottish Universities Physics Alliance (SUPA), Institute of Photonics and Quantum Sciences, School of Engineering and Physical Sciences, Heriot-Watt University, Edinburgh EH14 4AS, UK
²Renishaw Plc, Edinburgh EH14 4AP, UK
*H.Wright@hw.ac.uk

Optical Ranging Tools for Industry



Introduction– Industrial Applications: *Applications in Industrial Metrology*

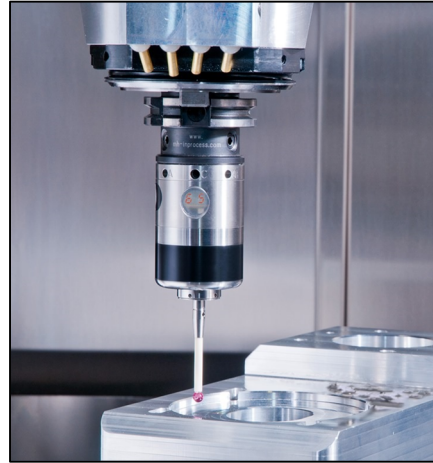
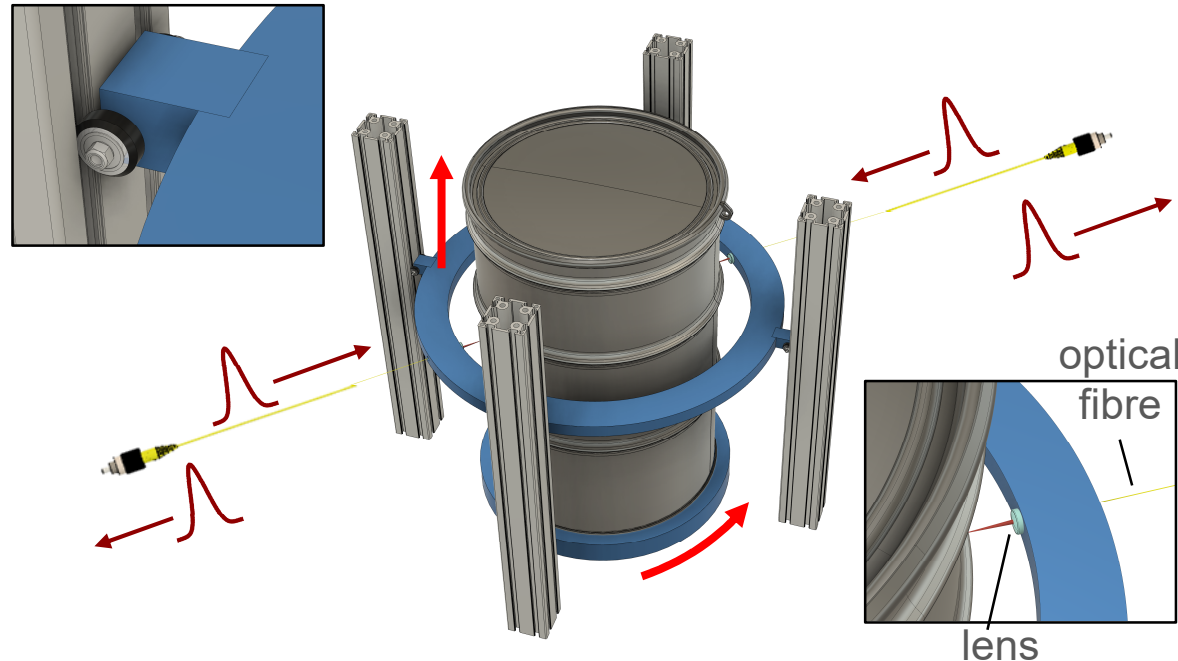
- Industrial priorities —
 - absolute distance measurement
 - robust to beam interruption
 - μm -level precision
 - rapid (kHz) update rates
- Machine-tool calibration
⇒ coordinate measurement machines (CMMs) or manufacturing robots
- Machine-tool motion verification
⇒ direct measurement of the end-effector (tool tip) instead of motor encoders
- Important for both Cartesian machines (e.g. CNC milling) and non-Cartesian machines (e.g. robot arms, hexapods)



Introduction– Industrial Applications: *Nuclear security and defence work*

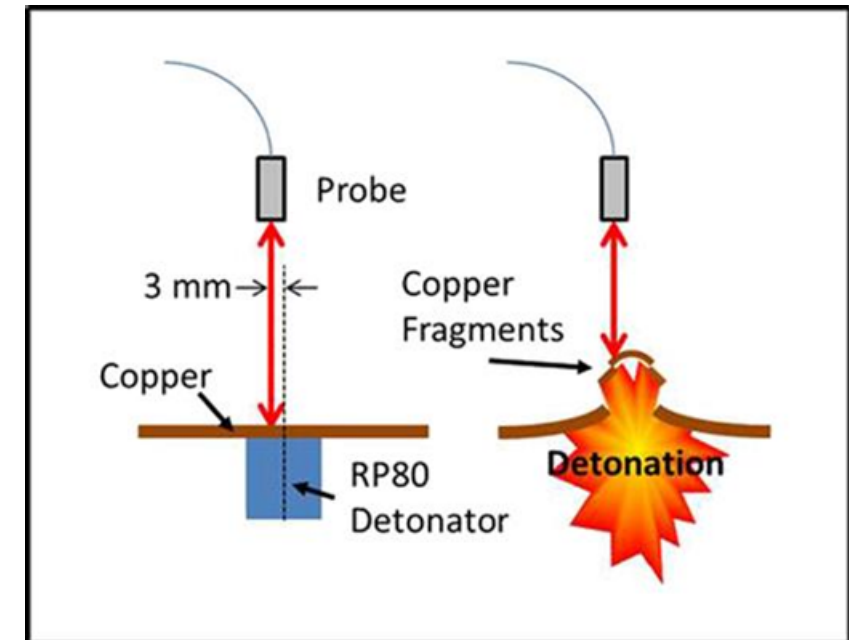
Dimensional Characterisation

- Aiming for accuracy $<5 \mu\text{m}$
- Alternative to touch probes / interferometry
- Characterisation of non-cooperative objects



Characterisation of Explosives

- Typically use pole-doppler velocimetry.



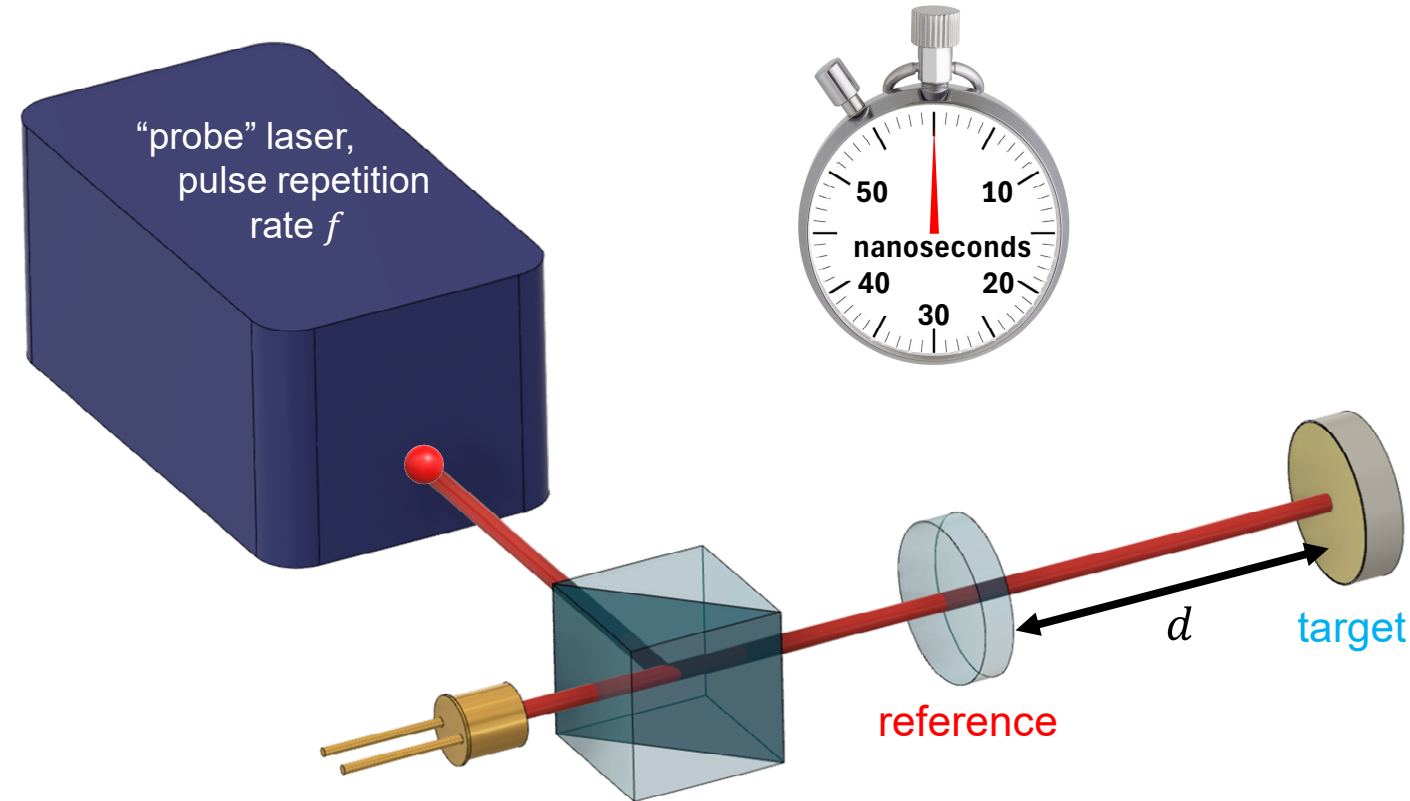
LaLone, *et al.* Rev. Sci. Inst, 2015

- Require high-repetition-rate lasers to enable sufficiently high-speed measurement ($\approx 20 \mu\text{s}$ acquisition time).

Two-photon dual-comb LiDAR – Optical Concepts:

Conventional time of flight LiDAR

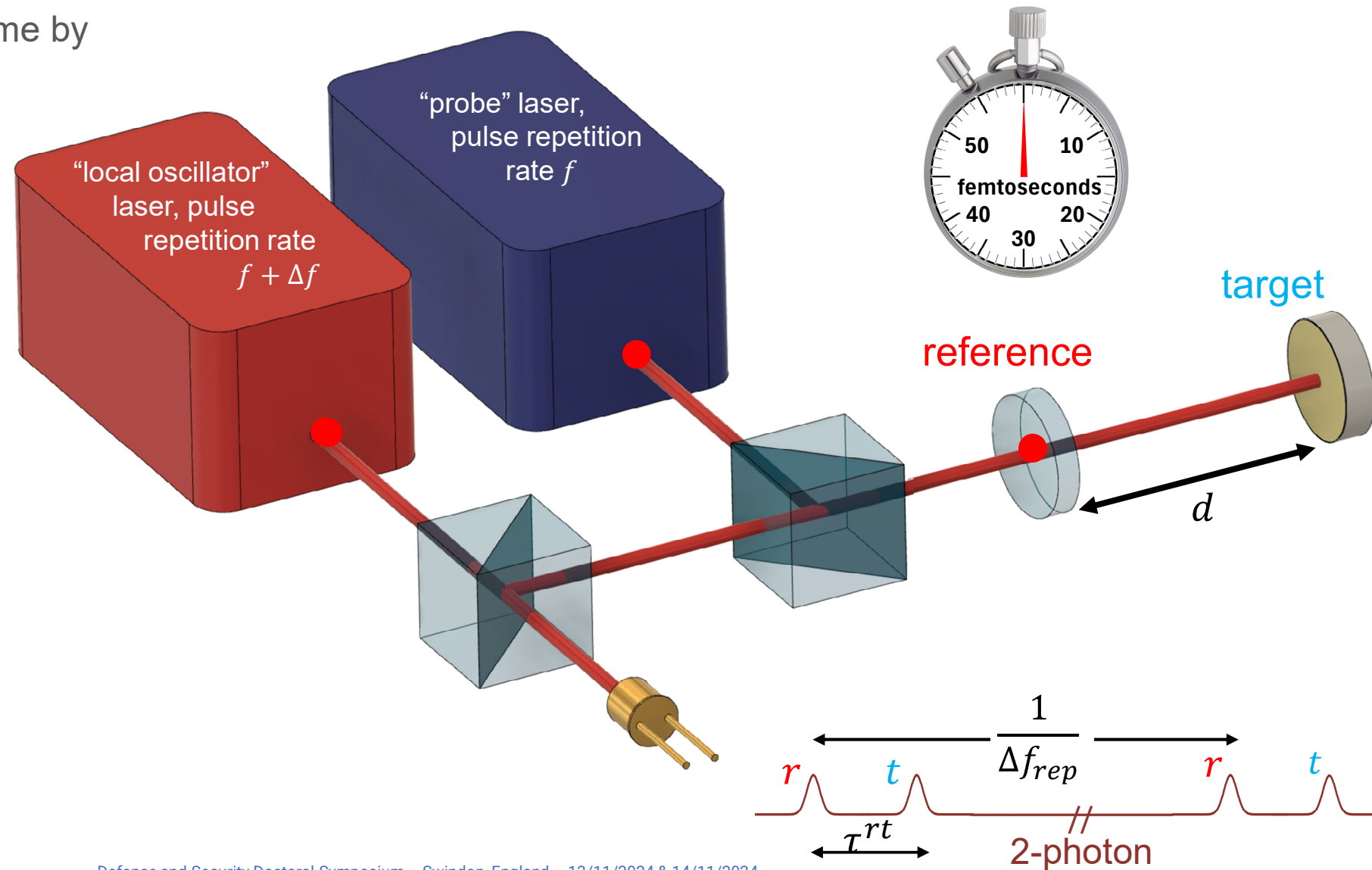
- Conventional LiDAR uses a pulsed laser + time-of-flight to measure distance.
- Pulses from reference and target optics start and stop the clock.
- Typical LiDAR electronic timers (≈ 50 ps resolution) limit precision to cm.



Two-photon dual-comb LiDAR – Optical Concepts:

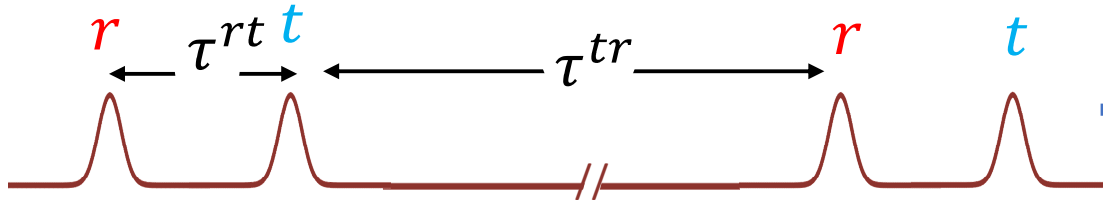
Two-photon dual-comb LiDAR

- Dual-comb measurement "stretches" optical time by factor $f/\Delta f$
- Same electronics $\Rightarrow$ **100-nm precision!**



Two-photon dual-comb LiDAR – Electrical operations:

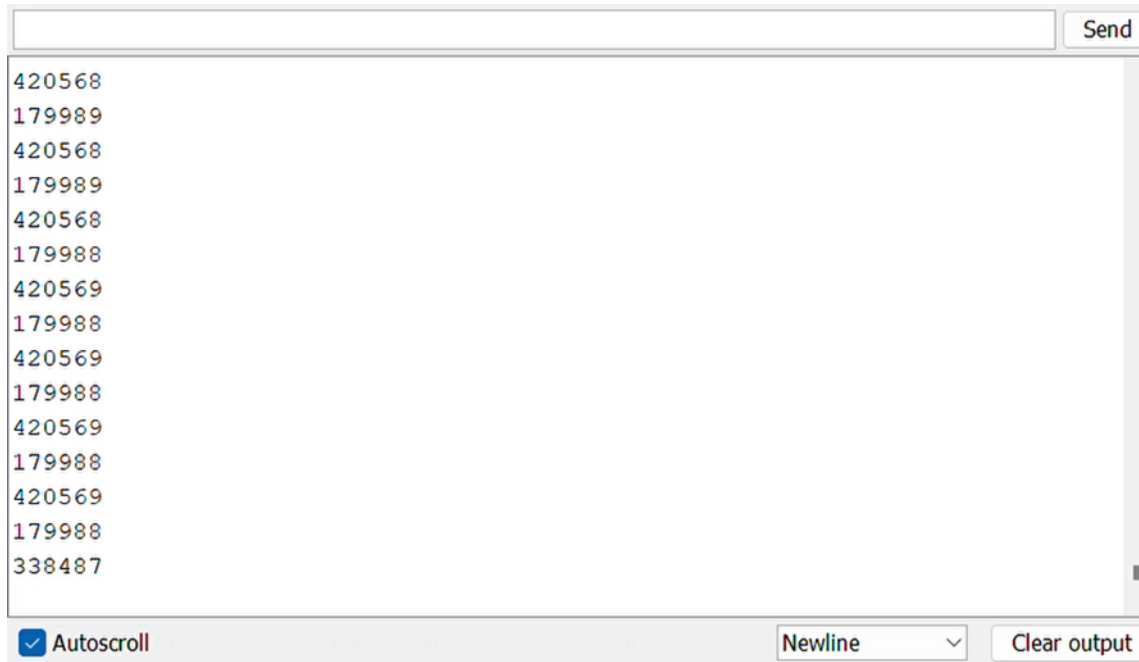
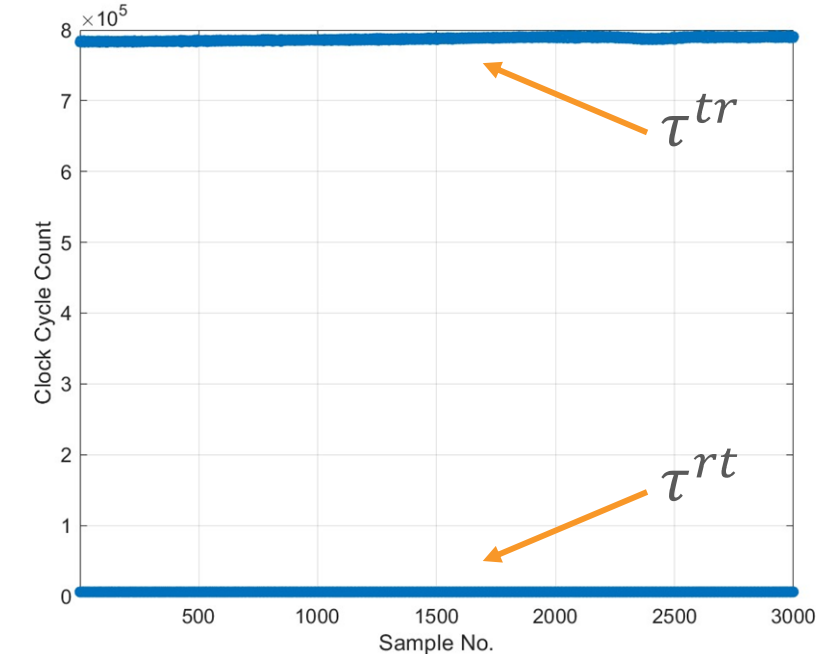
Electronic time tagging



- Arduino Teensy 4.0 counts internal 600 MHz clock cycles
- Saves and resets the count when a rising edge is detected
- Timing resolution = internal clock duration = 1.67 ns

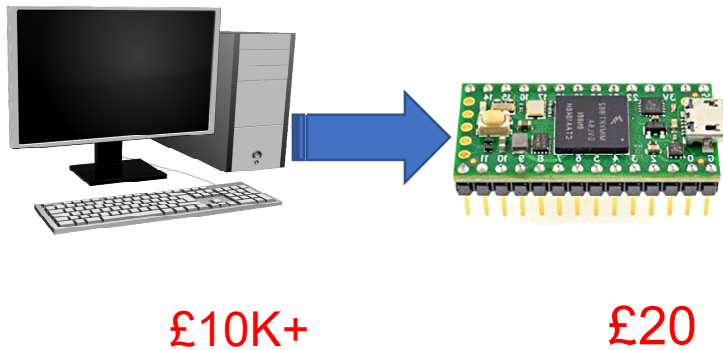
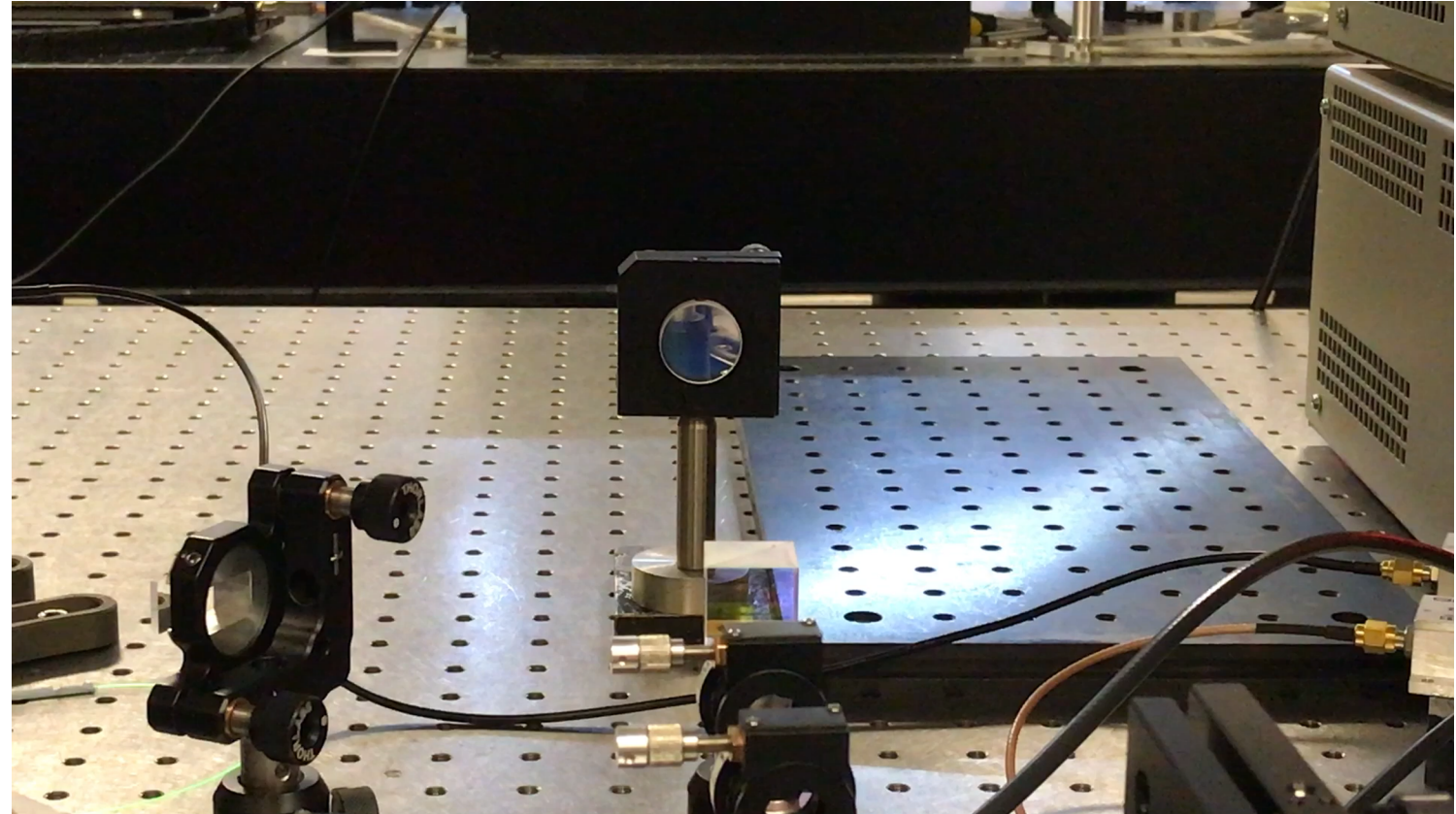
- "Time-tagged" pulses provide distance measurement:

$$d = \frac{c f_{rep}}{2} \cdot \frac{\tau^{rt}}{\tau^{rt} + \tau^{tr}}$$



Two-photon dual-comb LiDAR – Electrical operations: *Real time data and data burdens*

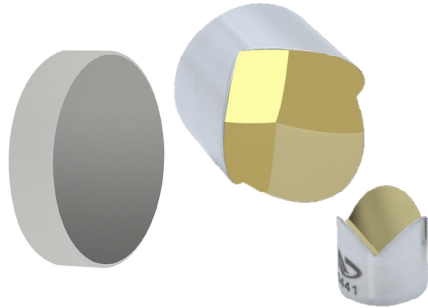
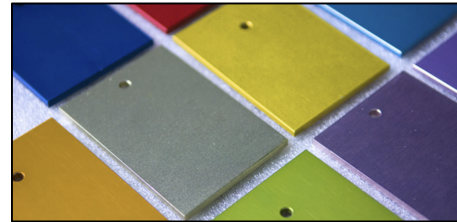
- Ultra-efficient data collection.
- Allows real time data results
- E.g. 25s of data costs:
 - 21GB for digitizer,
 - few 100kB for Teensy.



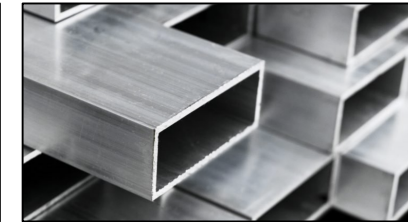
Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Towards non-cooperative targets

- Previous targets were mirrors / retroreflectors—what performance can we get from metal targets?



anodised

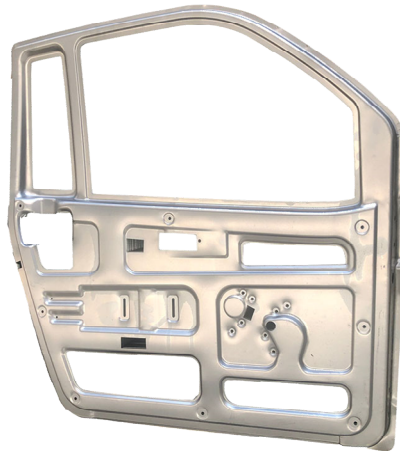


bare



painted

- Success in measuring non-cooperative targets will enable more potential applications...



Artefact characterisation



Explosive Shock Physics



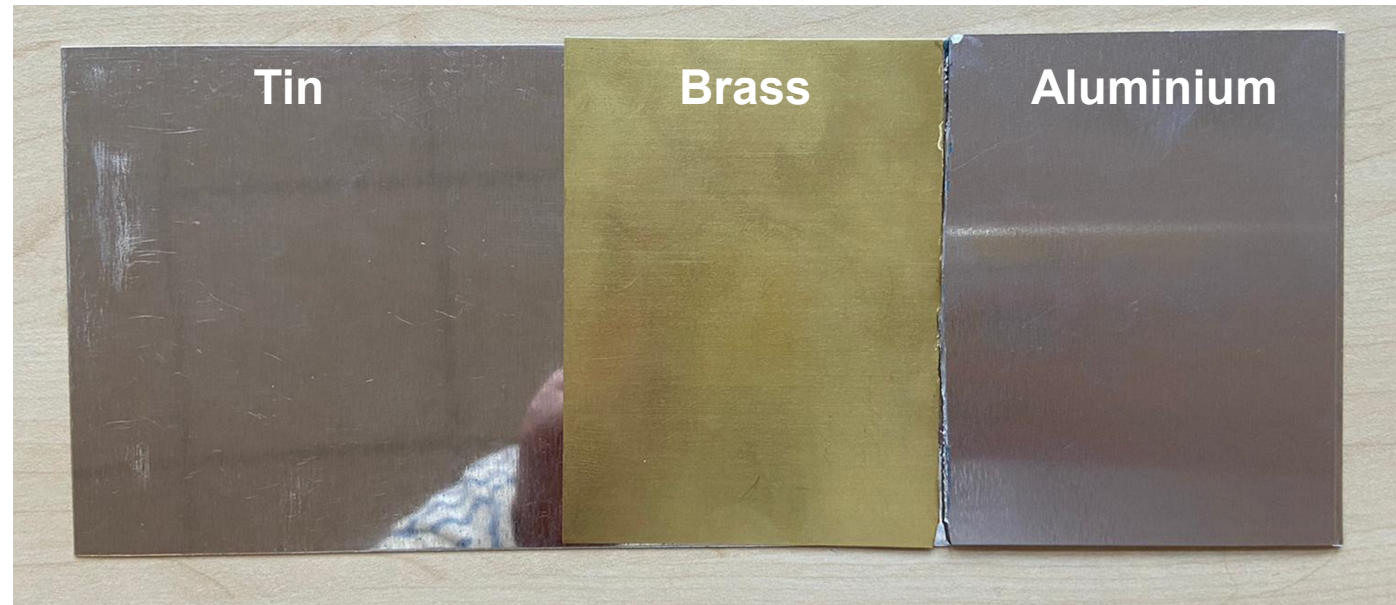
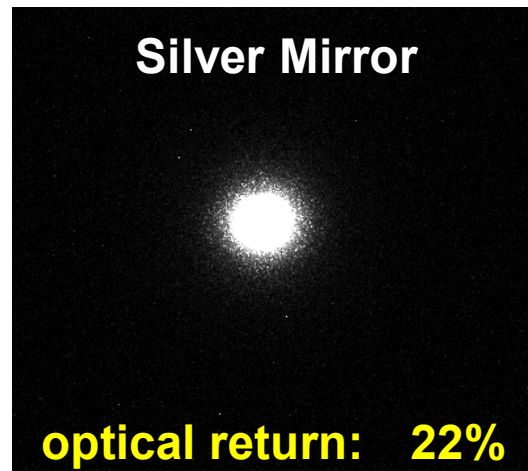
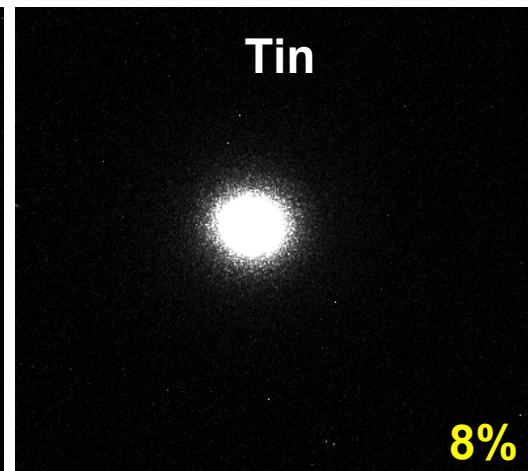
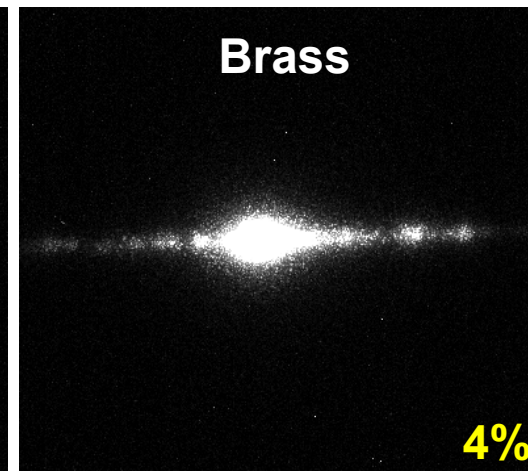
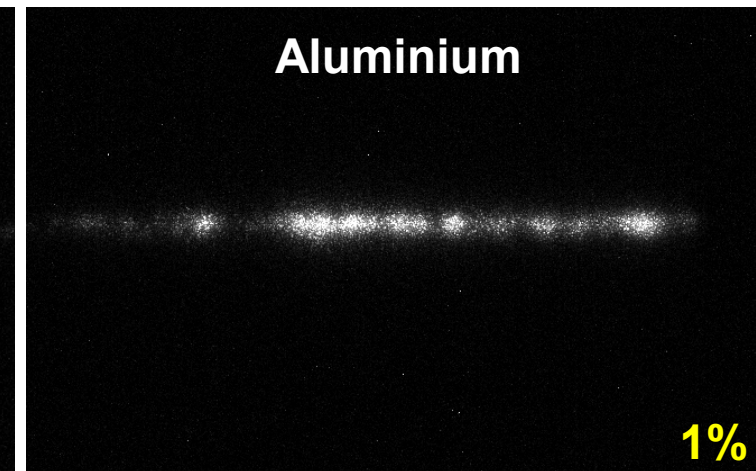
External position tracking of cartesian machines



External position tracking of non-cartesian machines

Two-photon dual-comb LiDAR – Uncooperative Target Measurements

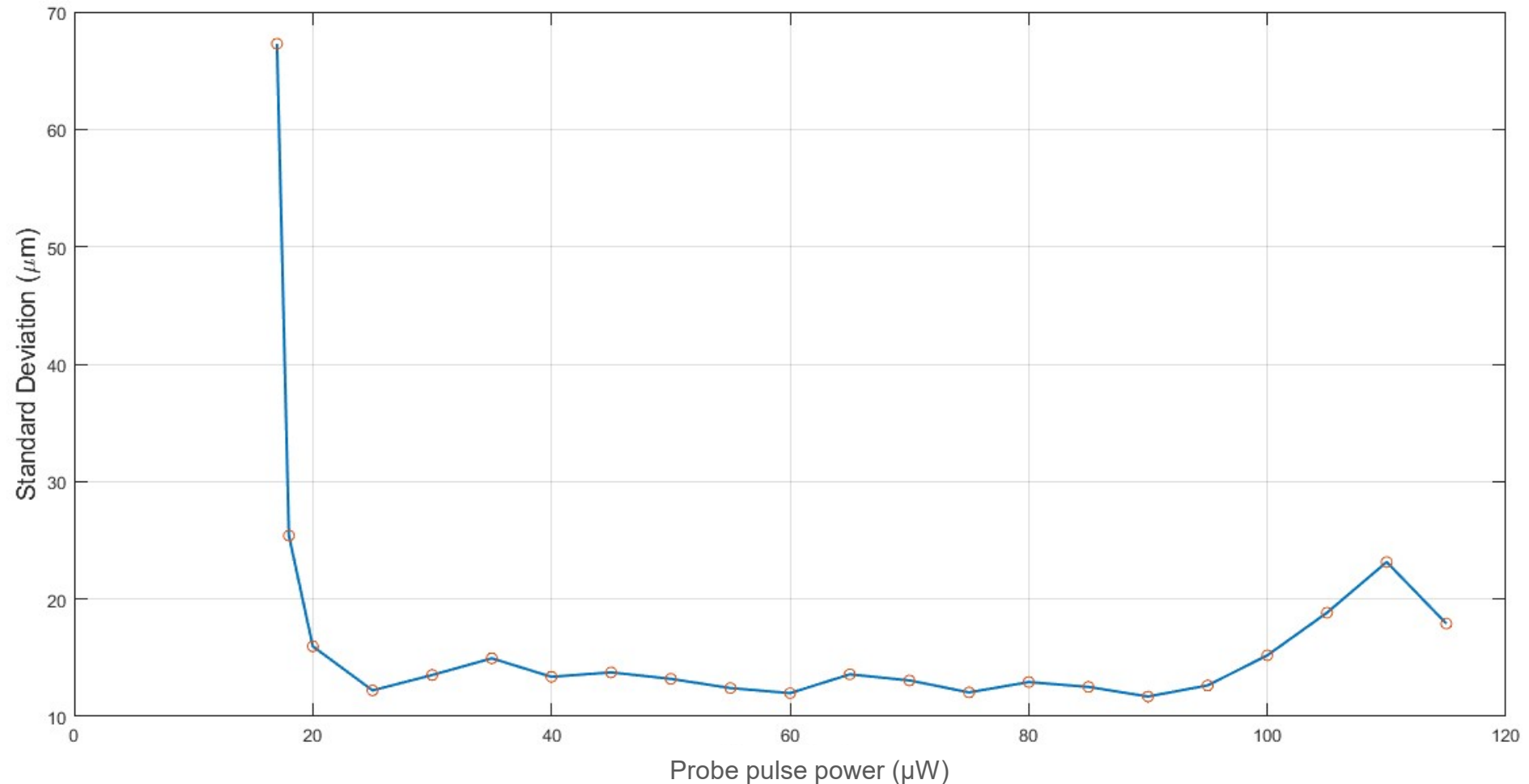
Non-cooperative targets: tin, brass and aluminium



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Impact of return power on precision

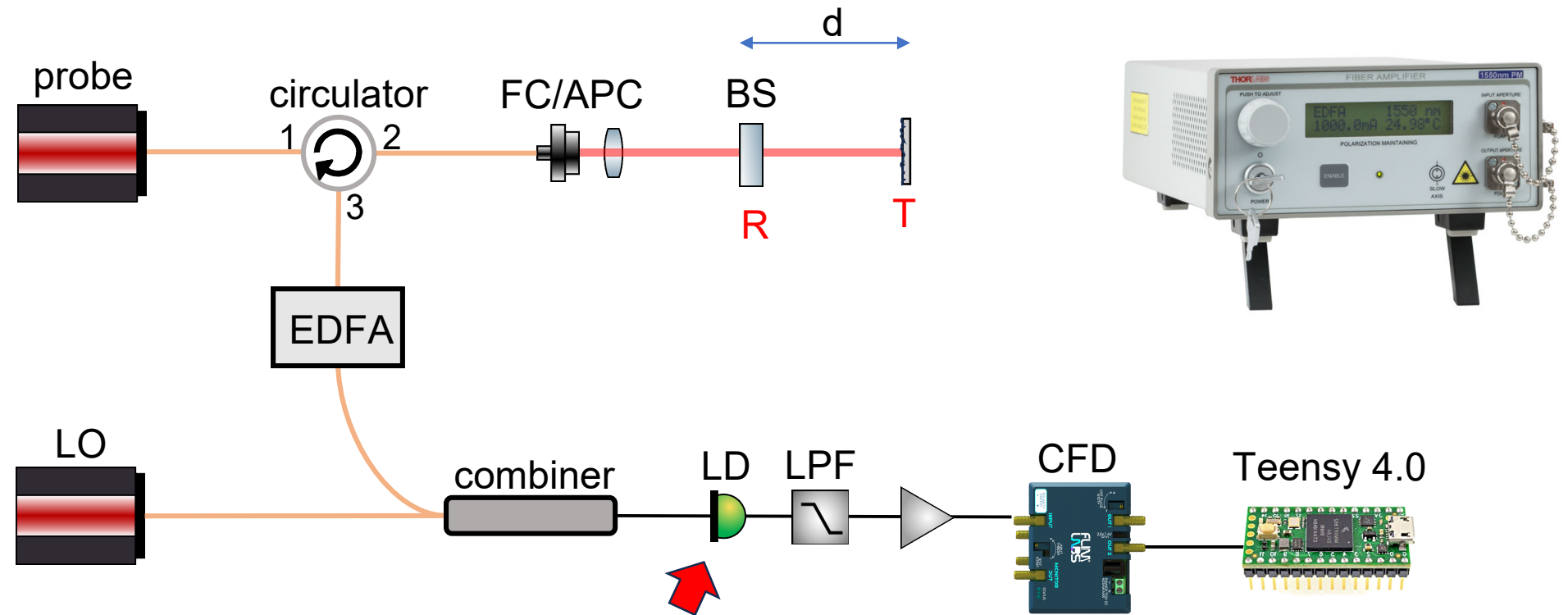
- Initial results (October 2024).
- Work in progress to investigate dependence on probe **and reference** pulse powers.



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Amplified detection

- Common transmit / receive geometry with in-path reference reflector
- Amplify weak reflections in EDFA to recover signal strength
- EDFA necessitates fiberised system



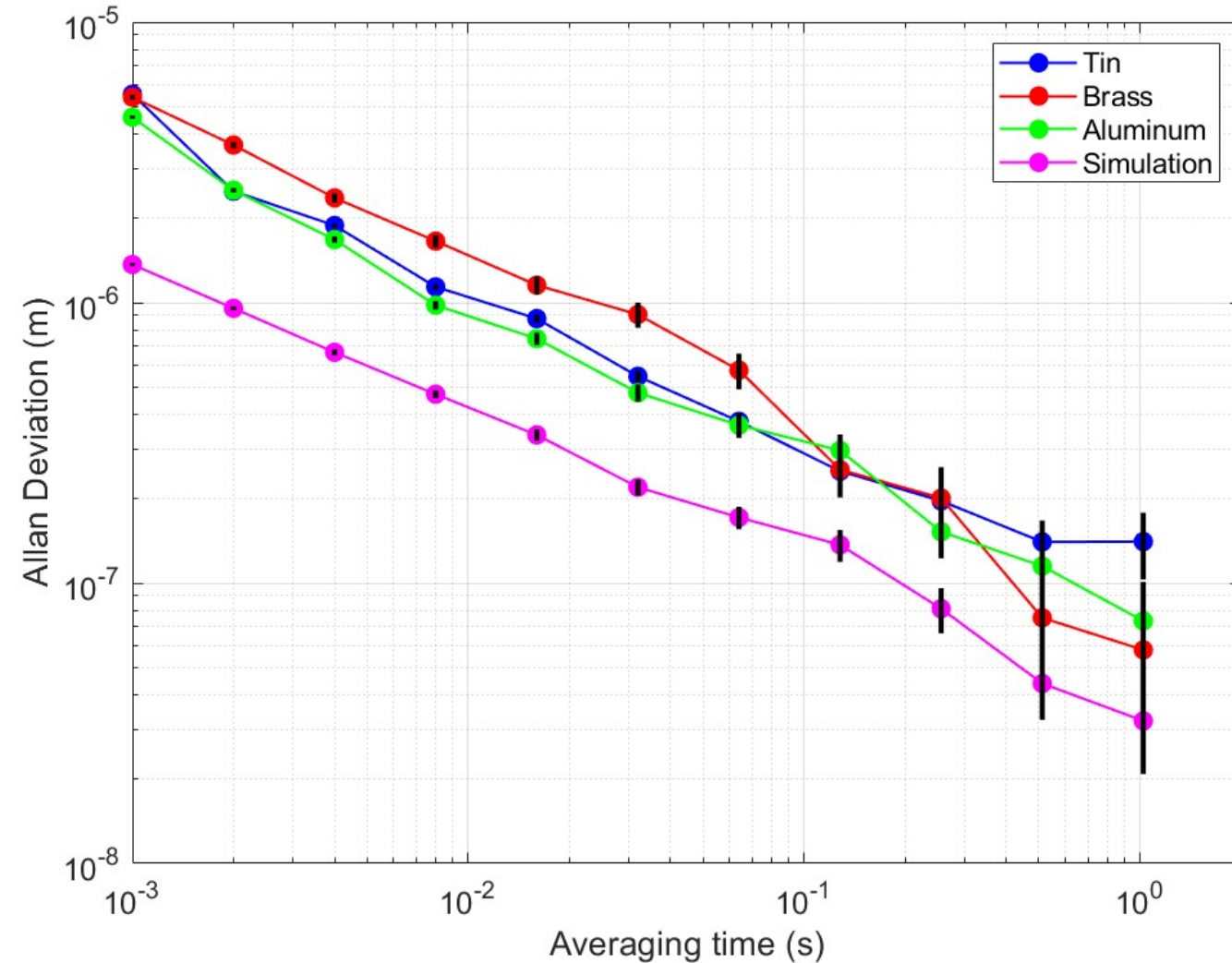
- Laser diode (LD) detector: Reid *et al.*, Appl. Opt. **37**, 8142 (1998); Sterczewski *et al.*, Nature. Commun. **14**:3339 (2023).

Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Measurement precision

- Allan deviations for measurements from tin, brass and aluminium at $\Delta f_{rep} = 1$ kHz

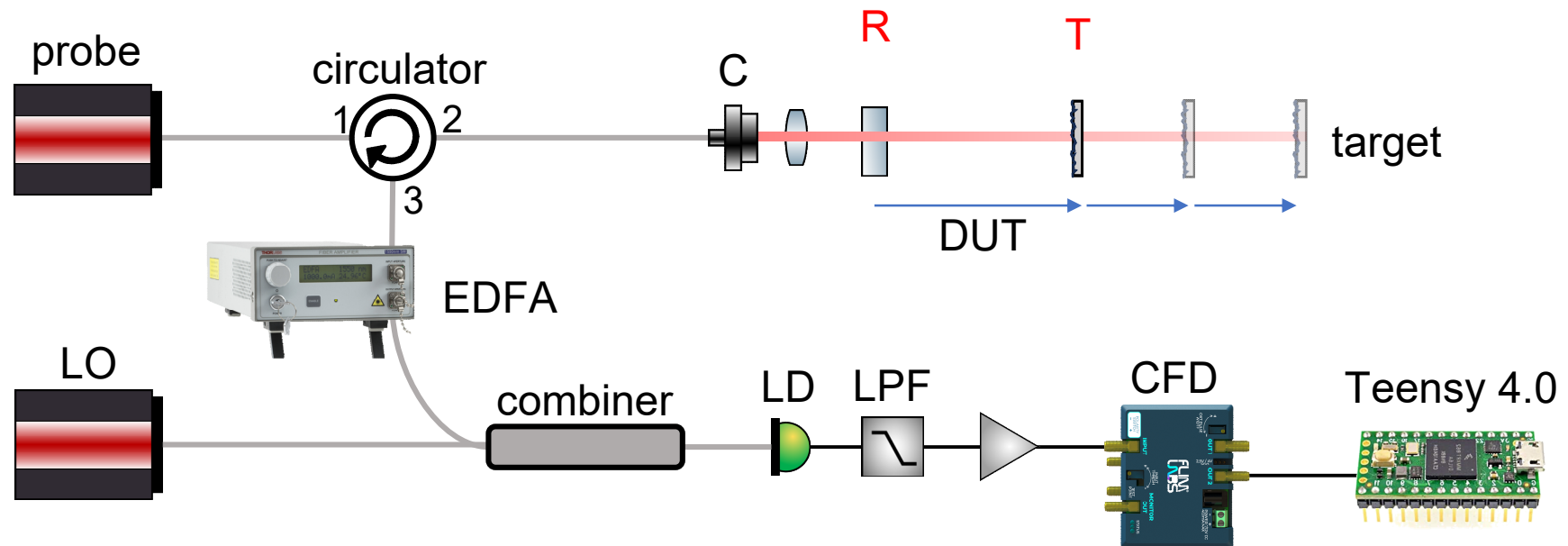
	Single-shot (μm)	1-sec aver. (nm)
Tin	5.5	141
Brass	4.6	73
Aluminium	5.4	58
Timing-limited precision	1.4	32



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Precision over increasing standoff distance

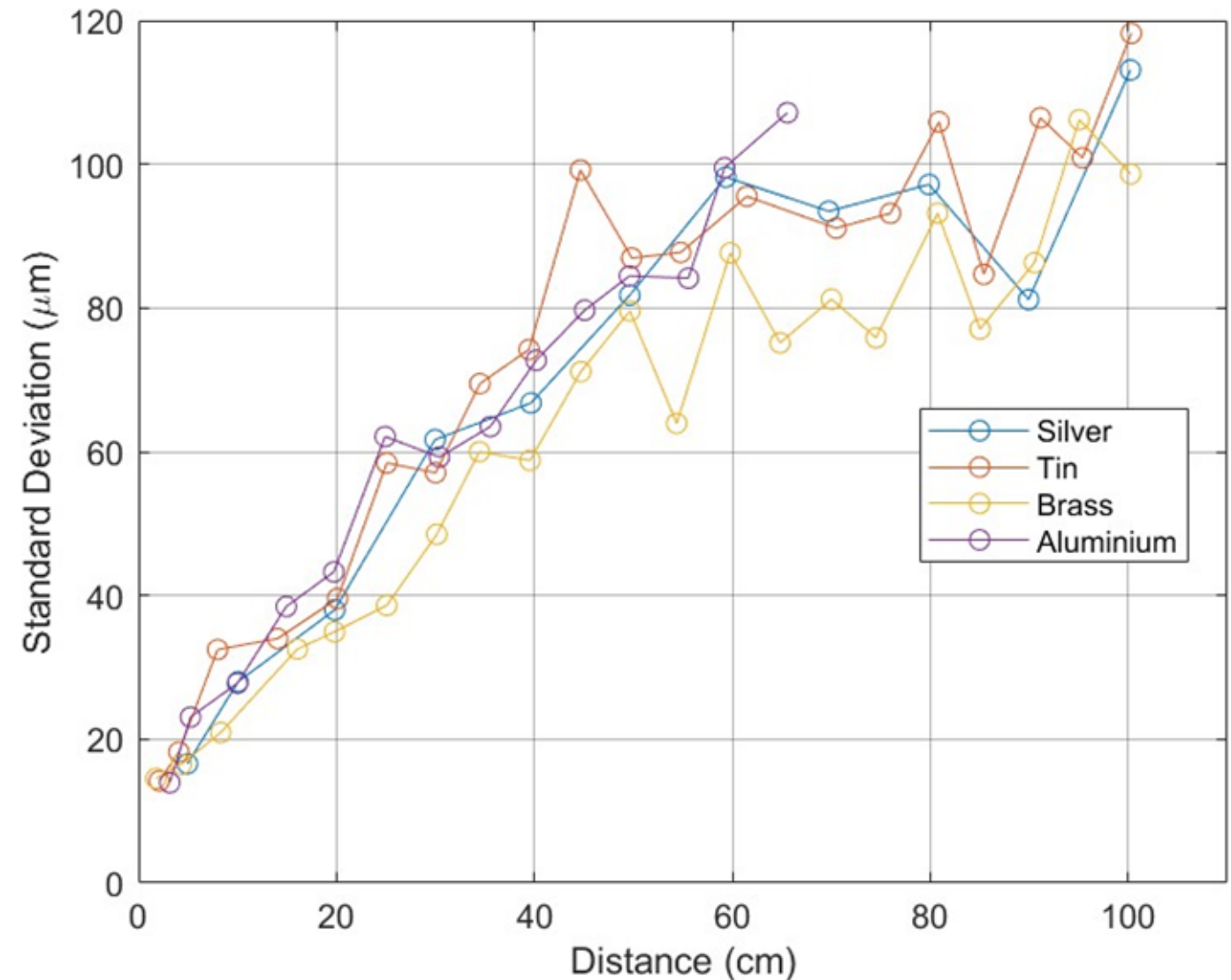
- Experiment to measure precision change over distance
- We noticed precision changed with the distance of the target in earlier work
- We believe this effect came from coupling inefficiencies due to fiberisation of our system



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Metal targets

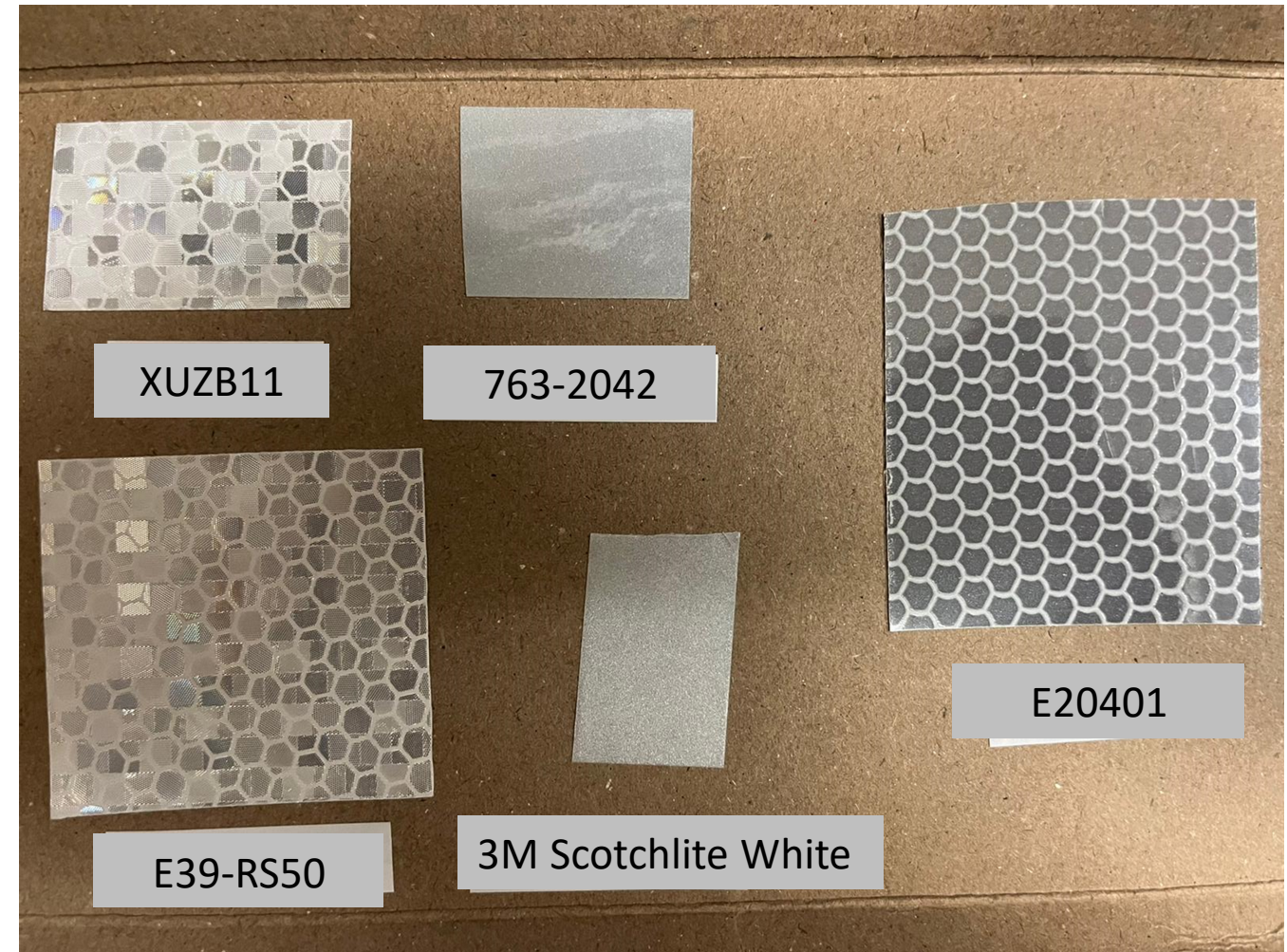
- A mirror was used as a control (marked Silver on the plot)
- Metals perform comparable to silver mirror
- Aluminium was most difficult metal to range
- A noticeable trend between distance and standard deviation



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Retroreflector tape

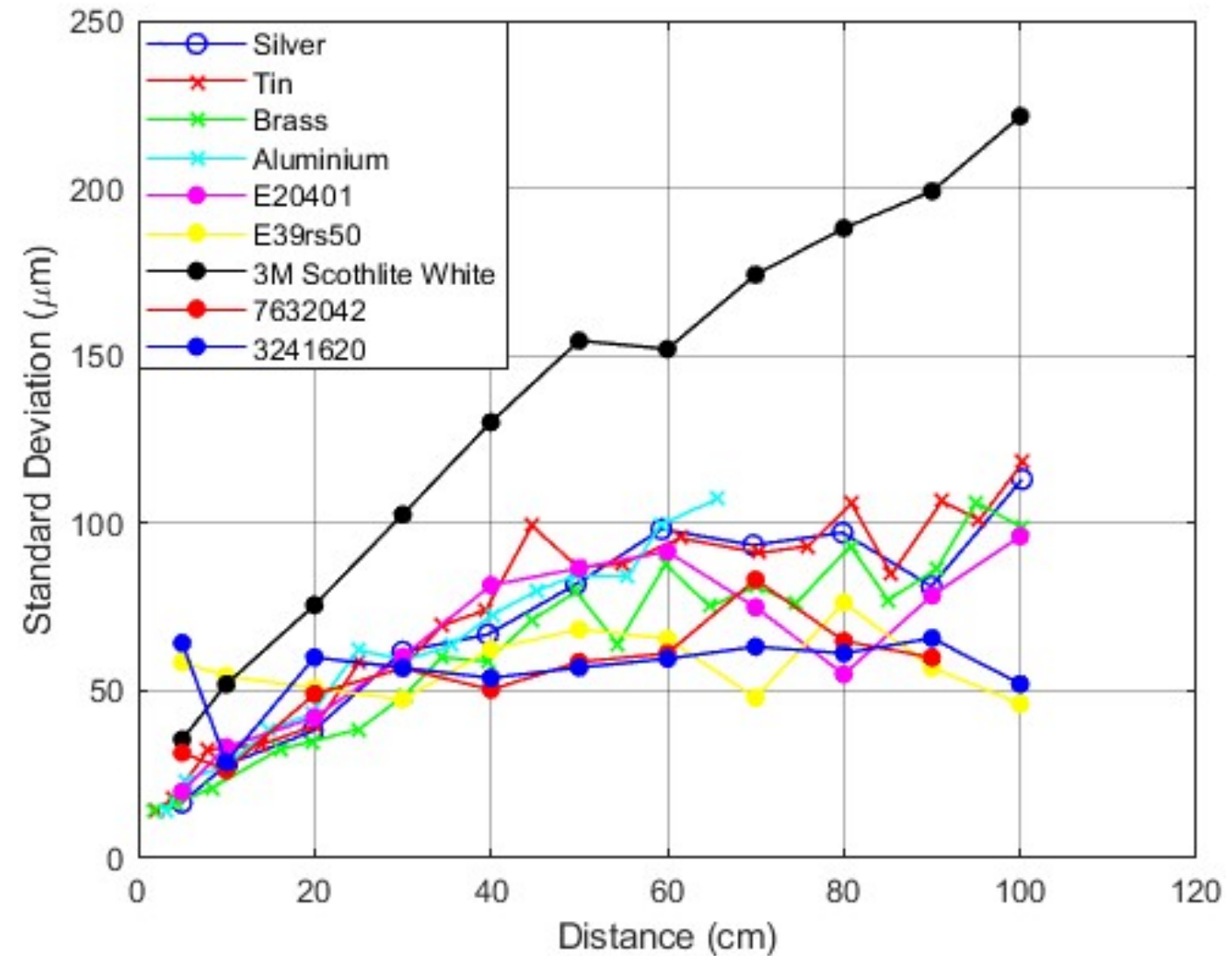
- As well as metal, retroreflective tapes were tested
- The tapes used were suggested by Renishaw PLC and AWE
- Commonly used in industry to aid in laser calibrations



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Variation of distance precision with range

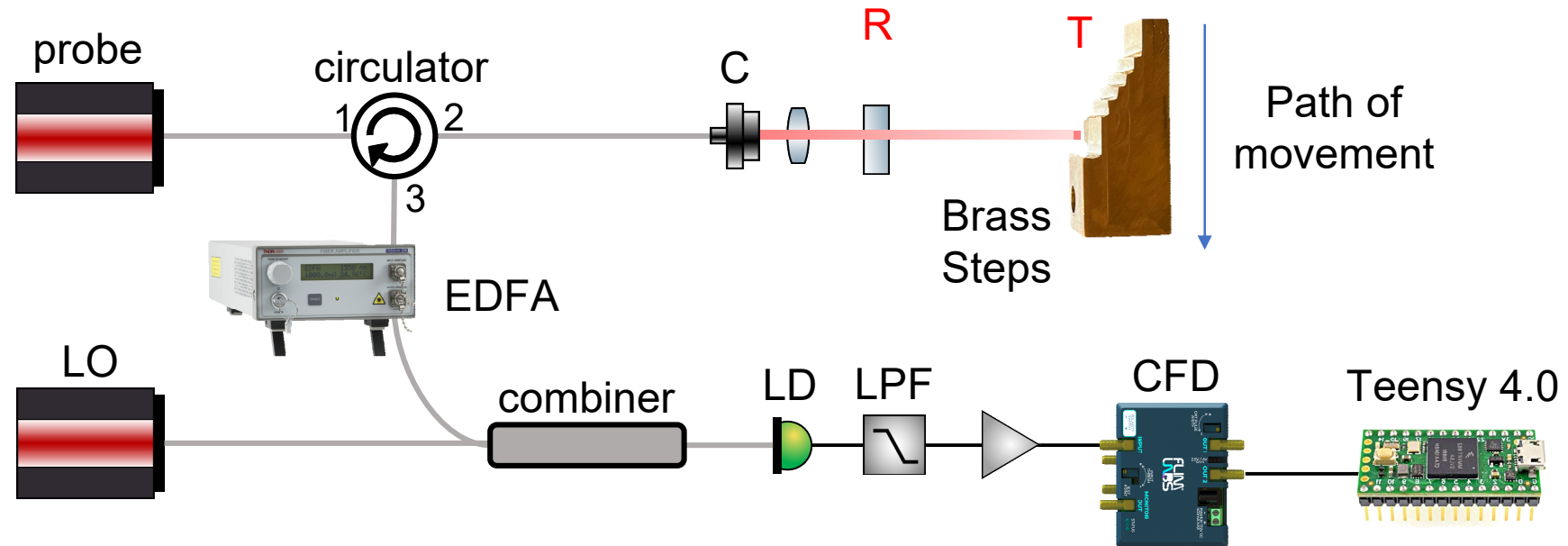
- A direct link to precision and target range is shown
- The retroreflective tape performance is equivalent to metal
- All materials precision worsened with increasing distance



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

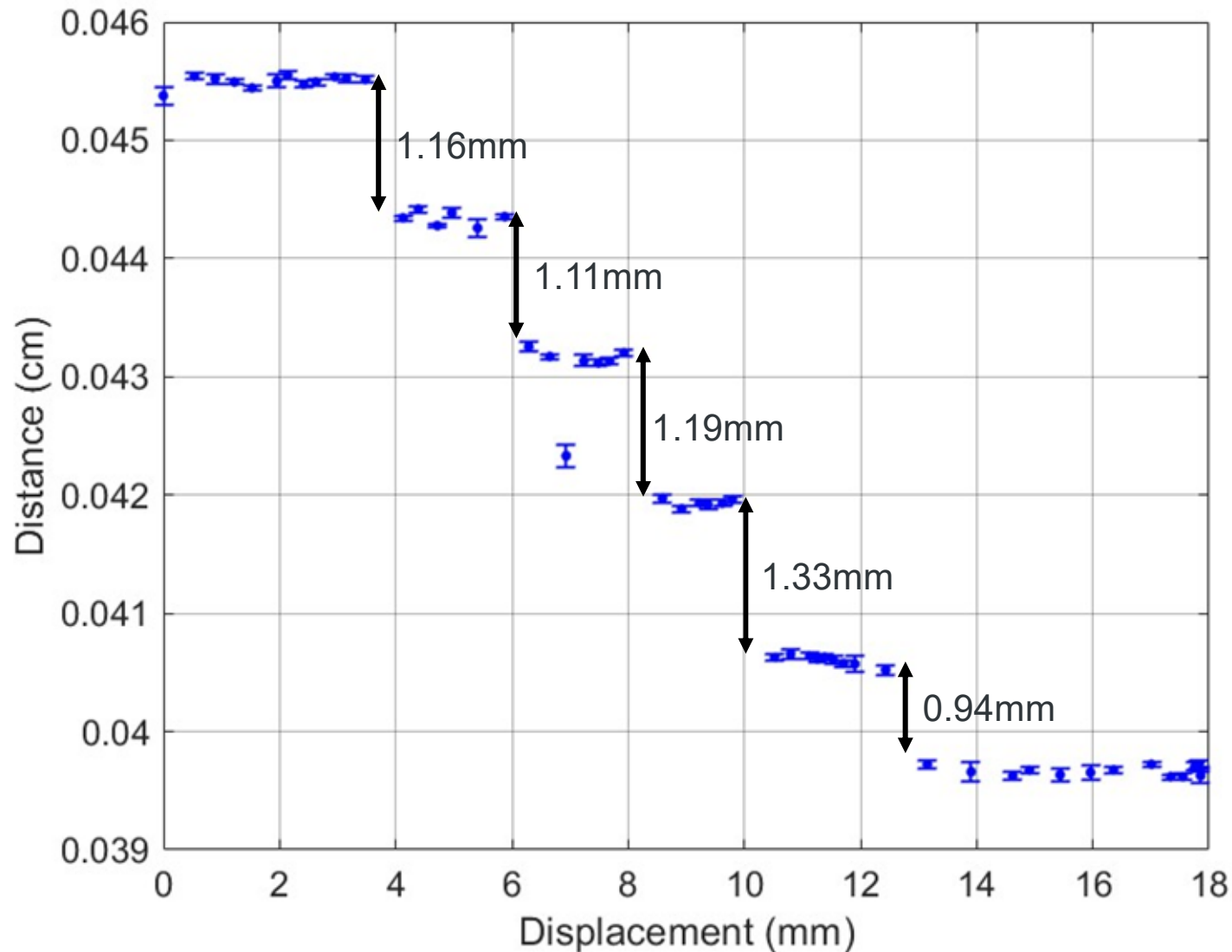
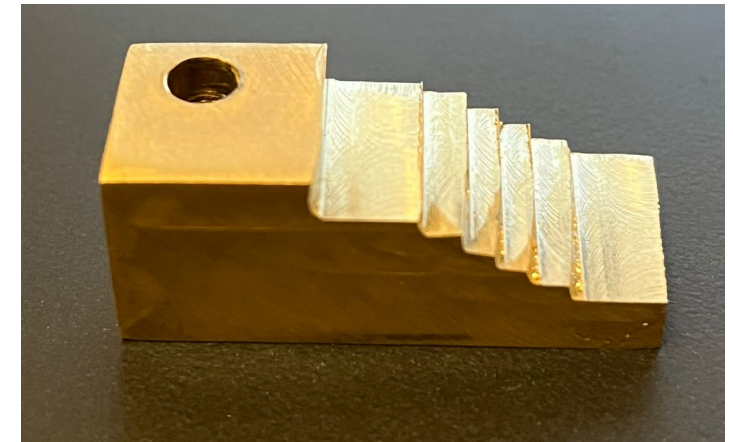
1-dimensional surface scanning

- Experiment designed to test surface scanning capability
- Each step was milled to be $1\text{mm} \times 1\text{mm}$
- If successful, allows work on 2-dimensional and 3-dimensional scanning to begin



Two-photon dual-comb LiDAR – Uncooperative Target Measurements

Extension to 2-dimensional profiling



Conclusions

- Demonstrated the ability to range multiple industry typical targets such as bare metals and retroreflectors.
- Instantaneous absolute precisions of a few μm possible.
- Sub-100-nm precisions possible from non-cooperative targets after 1 second of averaging.
- Proof-of-principle extension to 2-dimensional surface scanning.
- Represents a potentially powerful tool for supporting future MoD programmes in the realm of shock physics and industrial metrology.

Acknowledgements



(EP/L01596X/1,
EP/P006930/1 and
EP/N002547/1)



Meet the group

www.ultrafast.hw.ac.uk/



Wright, *et al.*, Optics Express **29**, 37037 (2021)
Wright, *et al.*, Optics Express **31**, 22497 (2023)